

Sediment vs Topographic Roughness: Antropogenic Effects on Acoustic Seabed Classification

Ruggero Maria CAPPERUCCI

MARUM, Center for Marine Environmental Sciences, University of Bremen, Leobener Str.

D-28359 Bremen

Department of Earth and Ocean Sciences, University of Waikato, Private Bag 3105, Hamilton, New Zealand

Marine Research Department, Senckenberg am Meer, Südstrand 40, 26382 Wilhelmshaven, Germany

Alexander BARTHOLOMÄ

Marine Research Department, Senckenberg am Meer, Südstrand 40, 26382 Wilhelmshaven, Germany

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INTRODUCTION

In recent years, environmental case studies of highly developed marine areas have become more relevant [Winter and Bartholomä, 2006; van der Veen and Hulscher, 2008]: for monitoring both the short- and long-term human impact on bio- and geo-sphere; for modelling the effects of such increasing pressure on ecosystem; as a key tool for environmental and socio-economic policy and management.

Among the different marine domains, coastal areas are the most accessible ones and the most difficult to be studied in detail, due to the complexity of natural and anthropic processes in action [OSPAR, 2008]. As a consequence, there is an increased demand for reliable high-resolution mapping tools, less dependent on expertise interpretation, and therefore more objective [Cutter, 2003].

In this scenario, the combination of acoustic, sedimentological and biological data is becoming the main approach for seabed habitat mapping studies [Brown, 2011]. Nevertheless, some specific aspects need further investigations: firstly, the analysis of acoustic data is still largely dependent on human expertise [Cutter, 2003]; secondly, repeated sampling technique is a standard procedure for biological studies but not a common practice for sedimentary research; and lastly, the ground-truthing process by means of sediment samples assumes that the point-based information can be consistently extended to the near vicinity of the sampling station. Besides, the positioning error/uncertainty is often not even mentioned as a key factor for assessing the reliability of the final seabed classification. The latter assumptions have to be proved for extremely heterogeneous environments, where anthropogenic impact increases significantly the disturbance (and, hence, the variability) of ecosystems.

In our study site of the Jade channel in the German Bight (southern North Sea) hydrodynamic conditions, topography, sediments and bio-communities are tremendously influenced by multiple human activities. Fishing and mussel farms are present [Herlyn and Millat, 2000]; the navigation channel is constantly monitored and dredged by the local harbour authority (Wasser- und Schifffahrtsamt Wilhelmshaven – WSA); moreover, a new container terminal (Jade-Weser Port, <http://www.jadeweserport.de/>) is under construction since 2008, with massive land reclamation, dredging and dumping operations. The Jade channel area represents, then, a unique site where to test the reliability of acoustic ground discrimination systems (AGDS) in a cumulative disturbed area.

The present study aims to address the following research questions:

- 1) What is the variability of repeated sediment samples in a highly heterogeneous environment?
- 2) How do the positioning error/uncertainty of sediment samples affect the ground-truthing process?
- 3) What drives the seabed classification in the different acoustic systems?

STUDY AREA AND METHODS

The Jade channel connects the Jade Bay with the German Bight (southern North Sea), being part of a wide tidal flat system that includes the Weser estuary (Figure 1).

The northern end (Outer Jade) is a mesotidal environment (*sensu* Hayes, 1975), with semi-diurnal tides ranging between 2.3 and 2.8 m, whereas the southern part (Inner Jade) is a macrotidal environment, with the tidal gauge reaching 3.9 m in Wilhelmshaven.

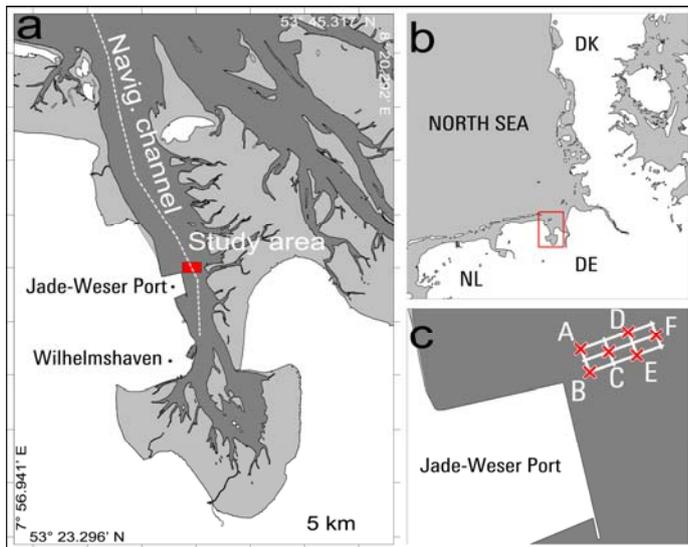


Figure 1 a) The Jade region, with the Jade-Weser Port and, in red, the study area. b) Location map of the Jade system. c) close up on the research site; white lines: main acoustic transects, red crosses: sampling stations

kHz) and a QTC 5.5TM system mounted on a Furuno FCV 1000TM single-beam echosounder (SBES, 200 kHz). All devices were deployed simultaneously along 7 main transects (3 approximately east-west and 4 approximately north-south oriented). Additional lines were collected for a complete MBES coverage and a denser SBES grid. A DGPS system with LRK correction was used for positioning. 6 stations were sampled (4 replications each) using a Shipek grab.

Data processing

MBES bathymetric data were processed using QINSyTM and a final 0.5x0.5 m grid was computed. DTM generation and seabed features mapping was done under Global MapperTM v13. A set of QTCTM software was used for acoustic seafloor classification: QTC IMPACTTM for SBES data, QTC SIDEVIEWTM for SSS data, QTC SWATHVIEWTM for MBES data, and QTC CLAMSTM for visualizing and editing classified data.

QTC IMPACTTM is based on a statistical analysis of the echo-trace shape, whereas QTC SIDEVIEWTM and QTC SWATHVIEWTM use statistical properties of backscatter images. The Automatic Clustering Engine function [QTC IMPACT User Manual, 2004], was used for splitting acoustic signals into a final number of classes that fits with the optimal split level suggested by the statistical parameters.

Sediment samples were analyzed following the procedure described by Wienberg and Bartholomä (2005) and classified using the GRADISTAT statistics package [Blott and Pye 2001]. The PAST software (Hammer 2001) was used for statistical analysis (Non-metric MDS and Cluster analysis). All the data were finally loaded in ArcGIS v9.2 for interpretation.

The sediment distribution shows a general decrease of the grain-size towards the high-tide line, with the finest sediments being located in the south-eastern part of the bay; the Inner Jade is characterized by the presence of fine sand; fine to medium sand occurs in the Outer Jade area [Kahlfeld and Schüttrumpf 2006]. Bedforms are commonly observed along the tidal inlet.

The research area covers approximately 0.8 km² in the Jade Channel, north-east of the Jade-Weser Port, partially within the old navigation channel. The water depth ranges between 14 and 26 m.

Acoustic data were collected aboard the R/V Senckenberg using a Reson Seabat 8125TM multibeam echosounder (MBES, 455 kHz), a dual-frequency Benthos 1624TM side-scan sonar (SSS, 110-390

RESULTS

Sedimentary data

Due to the strong tidal currents acting in the area, sampling positions were shifted with respect to the planned locations, the average distance between replications being 20 m (Table 1a). Station C shows the highest positioning error (average distance between replications: 32 m).

Sediments grain sizes range from coarse silt to very fine gravel (Table 1b), the main part (75%) falling into the sand fraction. Replications show significant difference in sediment composition: Station A presents the lowest variability, all the replications being dominated by sand. Station C, on the contrary, is characterized by the highest variability in composition, with the replication JSA04 muddy-based (47.6%), JSA09 totally sandy (91.8%) and JSA019 and JSA022 gravelly dominated (55.4% and 47.7%, respectively). Replications JSA02 and JSA14 (Station D) are the closest ones of the survey (distance = 2 m). Nevertheless, JSA02 presents a high content of mud (75.4%) and JSA14 is dominated by sand (60.1%). Similar results for Station E, where JSA10 is characterized by a 75.7% of mud, while JSA15 composition is mainly given by the sand fraction (76.6%), albeit they are only 7 m far.

Station	(av. dist=)	Sample	Gravel %	Sand %	Mud %	
Station A	(15m)	JSA07	17	17	20	A
		JSA18	14	18	18	
		JSA23	3			
		JSA05	28	18	28	
Station B	(20m)	JSA08	16	18	18	B
		JSA17			10	
		JSA06	32.5	59.7	7.7	
		JSA08	58.7	30.0	11.2	
Station C	(32m)	JSA09	37	39	50	C
		JSA19	19	20		
		JSA22	25			
		JSA02	38	2	13	
Station D	(21m)	JSA12	36	26	26	D
		JSA14			11	
		JSA04	19.2	33.3	47.6	
		JSA09	0.0	91.8	8.2	
Station E	(13m)	JSA10	4	11	23	E
		JSA15	7	19		
		JSA24	0.0	95.4	4.6	
		JSA03	0.0	25.7	74.3	
Station F	(16m)	JSA11	14	13	13	F
		JSA13	5	27		
		JSA21	0.9	66.3	32.8	
		JSA10	0.0	24.3	75.7	
JSA15	11.7	76.6	11.7			
JSA24	0.0	95.4	4.6			
JSA01	24.1	52.8	23.0			
JSA11	16.9	64.3	18.8			
JSA13	2.1	62.3	35.6			
JSA20	13.1	84.0	2.9			

Table 1a (left) and **1b** (right). 1a: average distance between replications. 1b: sediment grain size analysis, expressed as dry weight percent on total sediment.

The results of statistical analysis confirm that there is no significant correlation between sediment similarity and sampling closeness. In particular, only replications from Station A tend to group, while the already mentioned replications from Station D and E show low similarity values, in spite of their closeness (Figure 3a).

Acoustic data

The whole area is characterized by distinctive topographic features, mainly related to dredging operations. From West to East, 6 main morphological domains can be mapped (Figure 2):

- W: a wide area dominated by dredging marks related to the Jade-Weser Port construction phase;
- H: western high (min. depth: 14.4 m), without dredging scours;
- P: western pit (max. depth: 26.4 m), without dredging scours;
- N: old navigation channel, marked by regularly spaced and shaped dredging scours, elongated and parallels to the navigation channel;
- B: large bedform fields, mainly aside the old navigation channel;

- E: a wide domain characterized by the absence of dredging marks and by the presence of diffuse short-wave bedforms. It is the less disturbed area.

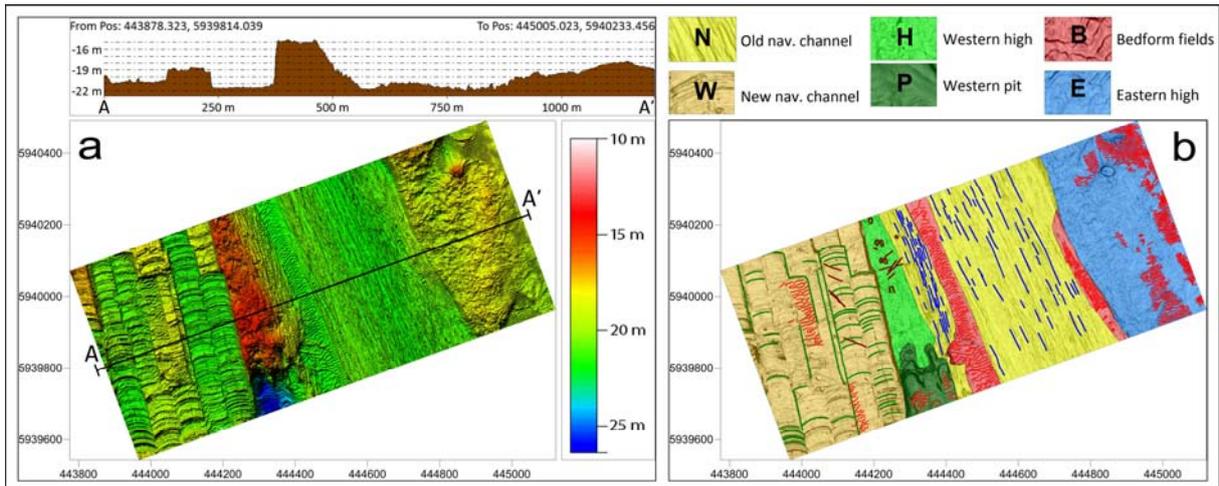


Figure 2: DTM of the research area (a) and main morphological domains (b).

The SBES final classification (optimal splitting level: 4) shows a patchy distribution of acoustic classes all over the area, with a dominance of the turquoise-colored class (42.2%) and brown-colored class (32.0%), which do not correspond to any morphological domain (Figure 3b). The pink-colored class (6.1%) is the only one focused around specific regions (H and P domains), while the blue-colored one (19.7%) is scattered all over the area, but scarcely represented in the same domains. All considering the extreme variability of sediment composition and distribution, the error in positioning and the patchiness of the acoustic classification, it is not possible to clearly correlate acoustic classes and sedimentary data.

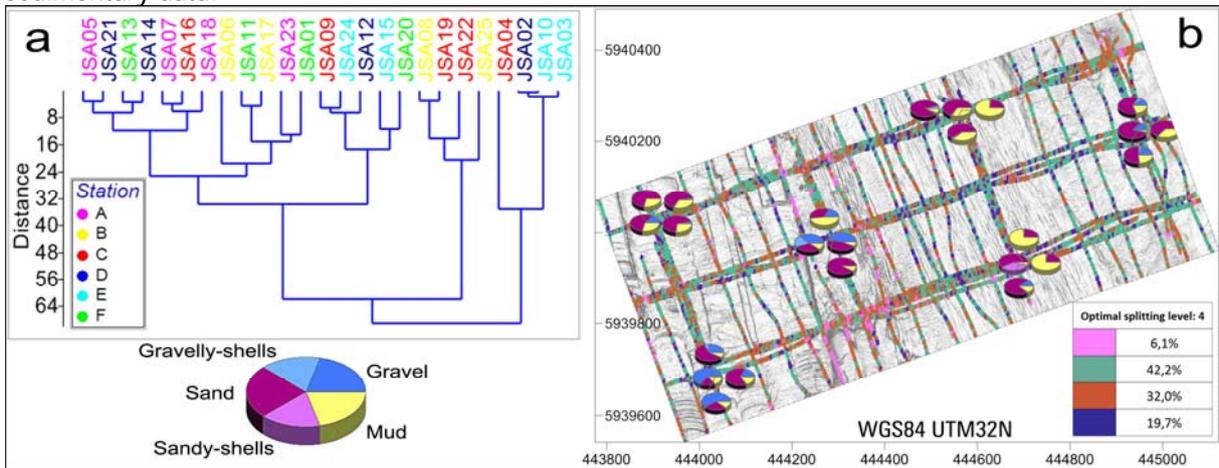


Figure 3: Clustering analysis, Euclidean similarity measure (a). SBES acoustic classification (b), overlaid by the sediment data.

The grey-colored class prevails (69,2%) in the MBES acoustic classification (optimal split level: 5. Figure 4a), marking both the western (W) and eastern (E) regions, including the B areas and with the exception of the H and P domains. 2 specific classes (light and dark blue-colored ones, 14,2% and 8,1%, respectively) cover the N morphological domain, where the green-colored class (2,8%) is also present. Thus, a correlation between main seabed features and acoustic classification is clear. The turquoise-colored class (5,7%) is spread all over the area. There is no correspondence between acoustic classes and sedimentary data: in fact, every acoustic class can be related to different sediment types and the same sedimentary group corresponds to more than one acoustic class.

The general pattern of the SSS classification (optimal split level: 4) follows the main morphological divisions (Figure 4b), with the green-colored class (36.3%) fitting the N area and the remaining classes distributed both in the western and eastern regions. The W domain seems to be equally represented by both the orange- (30.7%) and the violet-colored (24.0%) classes, while the E topographic area is mainly covered by the orange-colored class. The blue-colored class characterizes the slope between the H-P and N regions.

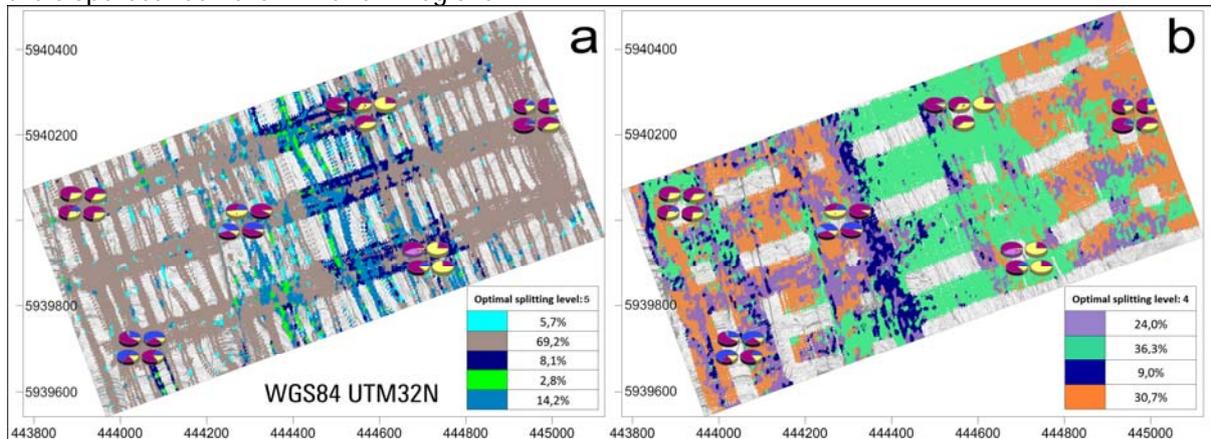


Figure 4: MBES acoustic classification (a) and SSS acoustic classification (b).

The same catalogue of 4 classes was used for classifying separately the 4 north-south and the 3 east-west SSS lines, showing significant differences. In particular, the area corresponding to the old navigation channel presents a homogeneous dominance of the turquoise-colored class in the east-west transects, whereas the same region shows a distinctive multi-class pattern parallel to the dredging marks in the north-south classification.

As for the MBES classification, the ground truthing process does not show any univocal correspondence between sediments and the SSS acoustic classes.

DISCUSSION AND CONCLUSIONS

Errors are always associated with sampling positioning. The mismatch between the planned and the sampled location can be negligible in homogeneous environment, giving a reliable classification. Punctual information can then be used for validating acoustic data even when the two sources does not perfectly overlap, assuming that the information inferred for a given position can be consistently extended to a certain neighborhood. This is not true for highly heterogeneous environments; in fact, repeated sampling clearly demonstrates that:

- Replications show significant differences in sediment composition;
- There is not clear relationship between positioning and similarity;
- Less disturbed areas (e.g. station F) present the same variability of directed multi-impacted ones (e.g., Station A), therefore there is no link between anthropic disturbance and heterogeneity.

The results show that repeated sampling is a must in such complex environments.

SBES classification reveals a highly heterogeneous seabed texture with no clear dominant pattern, thus being likely controlled by the distinctive patchiness in sediment distribution (=sediment roughness). Nevertheless, the extreme variability of sediment composition does not allow any interpolation: only the samples located exactly along the acoustic line could be theoretically used for ground-truthing, resulting in a scarcely sufficient amount of information. In conclusion, SBES classification is ruled by sediment patchiness, but the final classification can hardly be translated into sedimentological information.

On the contrary, swath-based systems (MBES and SSS) seem to be largely dependent on seabed topography for their classification, with acoustic classes that match the general division in morphological domains (= topographic roughness). MBES does not allow the distinction between W

and E regions, although they represent end members of highly disturbed and less disturbed environments. SSS classification not only stresses the different topographic domains, but also distinguishes between W and E regions. The angle between the acoustic lines and the seabed features is crucial for the final acoustic classification. In fact, regularly shaped and spaced features, like dredging marks, could lead to significantly different results.

In conclusion, mapping highly heterogeneous and disturbed environments is a crucial challenge for monitoring and protecting these extremely sensitive areas. Hydro-acoustic systems coupled with repeated sampling allow running this process in high resolution, but the resulting classification is mainly ruled by the sediment roughness for SBES systems and by topographic micro-roughness for swath-based devices. In any case, the resulting classes can only partially be linked to a proper sedimentological meaning.

CONTACT DETAILS

Ruggero Maria CAPPERUCCI
Marine Research Department, Senckenberg am Meer
Südstrand 40, 26382 Wilhelmshaven, Germany
Tel.: +49 (0)4421 9475212
Email: Ruggero.Capperucci@senckenberg.de

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